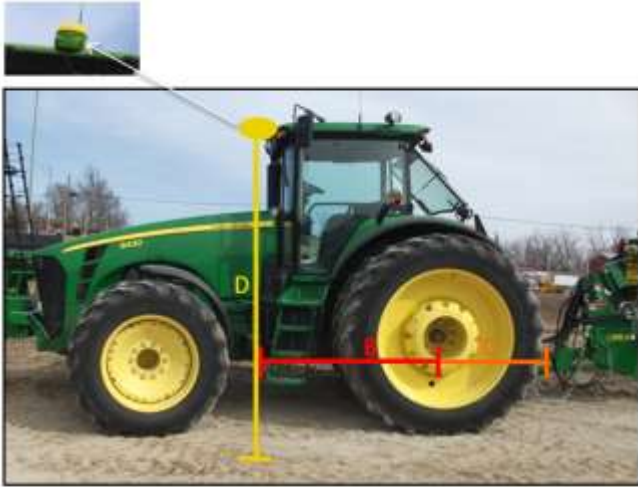


Measuring Machine Offsets



Machine Offsets

Non-Steering Location: Rear Axle

	<table style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 20px; text-align: center;">A</td> <td style="border: 1px solid black; padding: 2px;">0.0</td> <td style="font-size: small;">(in)</td> </tr> <tr> <td style="text-align: center;">B</td> <td style="border: 1px solid black; padding: 2px;">0.0</td> <td style="font-size: small;">(in)</td> </tr> <tr> <td style="text-align: center;">C</td> <td style="border: 1px solid black; padding: 2px;">0.0</td> <td style="font-size: small;">(in)</td> </tr> <tr> <td style="text-align: center;">D</td> <td style="border: 1px solid black; padding: 2px;">0.00</td> <td style="font-size: small;">(in)</td> </tr> </table>	A	0.0	(in)	B	0.0	(in)	C	0.0	(in)	D	0.00	(in)
A	0.0	(in)											
B	0.0	(in)											
C	0.0	(in)											
D	0.00	(in)											

A Lateral distance from center-line of machine to GPS receiver
B In-line distance from non-steering axle (machine turning point for track tractor) to GPS receiver
C In-line distance from non-steering axle (machine turning point for track tractor) to pivot point on implement hitch
D Vertical distance from the GPS receiver to the ground
 Note: Only used with Surface Water Pro applications

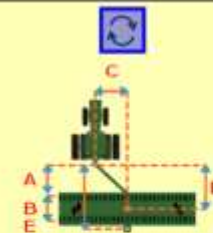
Accept
5:16pm

When measuring “D” (Receiver Height), measure from the ground to the line where green meets yellow.

- A: (This value is 0 unless the receiver is offset from the center of the machine)
- B: (Distance from Receiver to “non-steering” axle)
- C: (Distance from “non-steering” axle to the connection point (draw bar in this case))
- D: (Distance from ground to receiver. (height))



Offsets



A	0.0	(m)
B	0.0	(m)
C	0.0	(m)
D	0.0	(m)
E	0.0	(m)

A In-line distance from connection point to front of implement

B In-line distance from front to rear of implement

A+B = Documentation/Section Control location when in use

C Lateral distance from connection point to control point of implement

D In-line distance from connection point to control point of implement

E In-line distance from connection point to connection point for 2nd implement. Value only needed if second implement is used.

5:16pm

- A: (Tongue length from connection point to the front of the main bar (most consistent bar across the implement))
- B: (Front of main bar to seed tube)
- C: (This value is 0 unless the implement is offset or drawn off to the side ex. Windrower)
- D: (Measurement from the connection point to the lift wheels)
- E: (This value is 0 unless there is another implement behind the planter)